# Magnetic and cylinder sensors

### Magnetic proximity sensors

- Reliable and wear-free object detection
- Large sensing distances up to 60 mm
- Cylindrical and rectangular versions









|                                    | MFFM 08  | MFRM 08  | MFVM 08  |
|------------------------------------|--|--|--|
| features                           | <ul> <li>Acquisition of magnet location</li> <li>Large sensing range</li> <li>Object detection through container walls possible</li> </ul> | <ul> <li>Acquisition of magnet location</li> <li>Large sensing range</li> <li>Object detection through container walls possible</li> </ul> | <ul><li>Full metall sensor</li><li>Sensing distance to 60 mm</li></ul> |
| dimensions                         | 8 × 30 × 8 mm  | M8   | 8 × 12 × 30 mm   |
| nominal switching distance Sn typ. | to 60 mm   | 60 mm  | 60 mm  |
| switching frequency                | 5 kHz  | 5 kHz  | 5 kHz  |
| voltage supply range +Vs           | 10 30 VDC  | 10 30 VDC  | 10 30 VDC  |
| output circuit                     | PNP<br>NPN   | PNP<br>NPN   | PNP<br>NPN   |
| connection types                   | cable 2 m  | cable 2 m  | cable 2 m  |
| housing material                   | brass nickel plated  | stainless steel  | aluminum   |
| operating temperature              | −25 +75 °C   | −25 +75 °C   | −25 +75 °C   |
| protection class                   | IP 67  | IP 67  | IP 67  |

# Magnetic and cylinder sensors

### Cylinder sensors

- Detecting stop positions of pistons in every standard cylinder with C- or T-slots
- Different versions and versatile installation accessories for maximum flexibility
- Non-contact sensing and absolutely wear-free





|  | MZCK 03x1011<br>MZCK 03x1012                               | MZTK 06x1011<br>MZTK 06x1012<br>MZTK 06x1013  |
|--|--|---|
| features   | For C slot cylinders Oil- and salt water climate resistant | <ul> <li>For T slot cylinders</li> <li>Oil- and salt water climate resistant</li> </ul> |
| dimensions   | 3,7 × 23 × 4,6 mm<br>3,7 × 11 × 19,5 mm                    | 6,2 × 31 × 4,3 mm<br>6,5 × 21 × 9,4 mm<br>6,2 × 31,5 × 4,5 mm                           |
| nominal operation point / assured sensing distance Sa max. | 4 mT   | 4 mT<br>2 mT (MZTK 06x1012)   |
| switching frequency  | 200 kHz  | 200 kHz   |
| voltage supply range +Vs                                   | 6 30 VDC   | 6 30 VDC  |
| output circuit   | PNP<br>NPN   | PNP<br>NPN  |
| connection types   | cable 2,5 m<br>flylead connector M8                        | cable 2,5 m<br>flylead connector M8   |
| housing material   | PA 66  | PA 66   |
| operating temperature                                      | −40 +70 °C   | −40 +70 °C  |
| protection class   | IP 67  | IP 67   |

### Magnetic and cylinder sensors

#### Cylindrical and rectangularl design. Angular range 270...360°.

- Linearized analog output signals
- Resolution 0.09°
- Absolute sensing











|                          | MDRM 18   | MDRM 18  | MDFM 20   | MDFM 20   |  |  |
|--------------------------|---|--|---|---|--|--|
| features                 | <ul><li>Linear angular range<br/>270°</li></ul> | <ul><li>Linear angular range<br/>360°</li></ul>  | <ul><li>Linear angular range<br/>270°</li></ul>                 | <ul><li>Linear angular range<br/>360°</li></ul>                   |  |  |
|                          | Output signal 420 mA                            | <ul><li>Output signal</li><li>04.3 VDC</li></ul> | <ul><li>Output signal 420 mA</li><li>Resolution 0.09°</li></ul> | <ul><li>Output signal 04.3 VDC</li><li>Resolution 0.09°</li></ul> |  |  |
| dimensions (sensor head) | M18 x 1 (cyclindrical threaded)                 |  | $20 \times 30 \times 8$ mm (rectangular)                        |   |  |  |
| angular range            | 270° linear                                     | 360° linear                                      | 270° linear   | 360° linear   |  |  |
| resolution               | 0,09°   |  |   |   |  |  |
| working distance max.    | 5 mm<br>(with magnet rotor MSFS)                |  |   |   |  |  |
| output circuit           | current output                                  | voltage output                                   | current output  | voltage output  |  |  |
| output signal            | 420 mA  | 04,3 VDC   | 420 mA  | 04,3 VDC  |  |  |
| response time            | <4 ms   |  |   |   |  |  |
| connection               | cable 2 m<br>mating connector M12               |  | cable 2 m<br>mating connector M8                                |   |  |  |
| voltage supply           | 1530 VDC  | 4,77,5 VDC                                       | 1530 VDC  | 4,77,5 VDC  |  |  |
| operating temperature    | −40+85 °C                                       |  |   |   |  |  |
| protection               | IP 67   |  |   |   |  |  |
|                          |   |  |   |   |  |  |

## Functional principle

The heart of a magnetic magnetic angle sensor sensor is the integrated dual differential Hall element which builds an electrical parameter related to the flux direction of an exterior magnetic field. This magnetic field rotating about the element's center axis generates two sinusoids shifted by 90° which are utilized to detect the rotation angle for output as an absolute value. The integrated electronics evaluates the sinusoids into a linear voltage or current signal. The absolute dection principle ensures output of the correct rotation angle even after power failure.